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MODELLING AND CONTROLLING OF INVERTED PENDULUM



LAP Lambert Academic Publishing Apr 2018, 2018. Taschenbuch. Condition: Neu. Neuware - The inverted pendulum is a highly nonlinear and open-loop unstable system. This means that standard linear techniques cannot model the nonlinear dynamics of the system. Inverted pendulum system is often used as a benchmark for verifying the performance and effectiveness of a new control method because of the simplicities of the structure. In this paper an accurate model of the inverted pendulum system, a neural network controller and...

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